

# Development of a Hand-Held Device for Automatic license Plate recognition

<sup>1</sup>Harshith Sand <sup>2</sup>Anusha Balehola <sup>3</sup>Prasanna Kumar M

<sup>1</sup>Student, Electronics and Instrumentation Engineering, Dr. Ambedkar Institute of Technology, India;

<sup>2</sup>Student Electronics and Instrumentation Engineering, Dr. Ambedkar Institute of Technology, India

<sup>3</sup>Associate Professor, Electronics and Instrumentation Engineering, Dr. Ambedkar Institute of Technology, India

Submitted: 01-12-2021

Revised: 12-12-2021

Accepted: 15-12-2021

## ABSTRACT

In the last few years, Automatic Number Plate Recognition (ANPR) systems have become widely used in the safety, the security, and the commercial aspects. Forethought, several methods and techniques are computing to achieve the better levels in terms of accuracy and real time execution. The details of development of a hand-held security device to help the security people at the entrances of big institutions/industries/apartments. The security people can scan the number plate of vehicles come at the entrance using this device and the device will display whether the vehicle is authorized or unauthorized to enter to the premises. Provision is given to add/remove the registration number to/from the database. This device is designed around onboard computer, which is commonly termed as Raspberry Pi. The optical character recognition technique (OCR) implemented on this device is used for the identification of the registration number. This project aims to recognize the license number plates, OpenCV has been used to identify number plates and python to extract characters and digits from the number plates. OpenCV is an open-source machine learning library and provides a common infrastructure for computer vision. **Key Words:** Raspberry pi, Automatic license plate recognition (ALPR), Optical character recognition (OCR), RGB colored, Morphological output.

## I. INTRODUCTION

In smart cities, security is a real concern and smart methods for ensuring security are to be implemented. Monitoring vehicles entering into restricted areas such as institutions, industries, apartments etc. are a real concern. Checking the authenticity of these vehicles for security purposes is a difficult task as the number of vehicles to be monitored is very large. It is time consuming for a security person to physically check every vehicle and it is error prone. Auto

matic license plate recognition (ALPR) algorithms are used for this purpose. It became much interest during the last decade along with the improvement of digital camera technology and the computational processing. ALPR can be used in many places such as vehicle entry and exit gates, Parking, Toll booth etc. ALPR is an image processing technology used to identify vehicles by their license plates. The system uses a camera to take the image of the vehicle, then an image processing software analyses the images and extracts the number plate information. The extracted number can be used for monitoring, authentication etc.

Many license plate algorithms have been proposed in the literature. Although license plate recognition methods have been studied extensively for many years, it is still a challenging task due to different factors involved in it which would effect its end result, have developed an android application which can extract license plate number in machine-encoded text type from image captured by mobile camera. Another implementation of ALPR system on android mobile phone can be seen.

The literatures talk about an algorithm implemented for vehicle plate localization, segmentation and recognition in real life scene. An edge based multistage approach to the license plate localization from video snap shots of registered vehicles is presented. Different methods for license plate recognition in Indian vehicles are described. Most of the studies in the literature talk about a computer-based implementations. Very few attempts have been for implementing such algorithms in hand held devices. The commonly available implementation for making a hand-held device for license plate recognition is to implement the algorithm on mobile phones. But it is studied that even though possible to achieve an accuracy of 90%, the processing power of mobile devices is still less compared to PC based systems. Processing time can be of concern in such systems. Another way of developing a portable

device is to implement on single board computers. A portable device for automatic license plate recognition will definitely help security people. In this device, license plate of vehicle is captured by using Pi camera. The status of authorization of vehicle will be displayed on TFT screen by comparing extracted number with an available database. Provision is given to add numbers to the database, if needed.

## II. PROPOSED SYSTEM ARCHITECTURE

The block diagram to depict the construction of realtime Hand-held device for Automatic License Plate Recognition shown in Fig 1. It consists of a powersupply, camera module, P10(1r)-v706 LED display, anEthernet shield. The main component used here is theRaspberrypi3.0

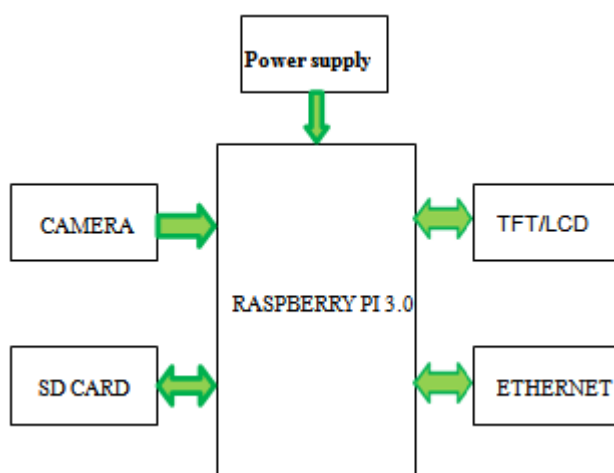


Fig 1. Block diagram

### 1.1 Methodology

It is proposed to design a hand-held device for the use of security persons for automatically recognizing the license plates of vehicles in front of them. The system is implemented based on raspberry pi-3 board. A Pi camera and a TFT touch screen are attached to this. The general block diagram of the system is shown in the above figure. In this device, license plate of a vehicle is captured using Pi camera. This captured image is processed to extract the number. The status of authorization of the vehicle is displayed on the TFT screen by comparing the extracted number with an available data base. Provision is given to add number to the database when unauthorized vehicle detected.

Raspberry Pi acts as core of the Hand-held SecurityDevice. The device is designed around this on-boardcomputer,whichcanefficientlycommunicate with the input and output modulesattachedtoit.Theimageofthenumberplatedetail s is fed as input to the processor. TheProcessor takes responsibility to check theauthentication details of every vehicle. Allremaining hardware components are connected tothisboard.Whenever a vehicle arrives at the entry gate of the Institute, its authorization was checked using this device by taking the image

containing its license plate. It is to be noted that, an option to add an unauthorized number to the database is also given in the GUI. When this option is pressed, a higher official will be notified the detection of an unauthorized vehicle through cloud communication. He will be able to add the number of this vehicle into the data base of authorized vehicles.

### 1.2 Working Principle

The functioning process includes 3 main process, namely, Pre-processing, Extraction of Characters and Recognition using template matching.

### 1.3 Pre-Processing

Pre-processing has RGB to grey conversion, Morphological process, Convolution and Thinning of images. And then the characters are extracted by OCR technique and compared.

#### 1.3.1 RGB to Grey

There are a number of commonly usedmethodstoconvertanRGBimage to a grayscale image such as average method andweightedmethod. The Average method takes the average value of R, G, and B as the grayscale value.  $Grayscale = (R + G + B) / 3$ .

Theoretically, the formula is 100% correct. But

when writing code, you may encounter overflow error. The average method is simple but doesn't work as well as expected. The reason being that human eyes react differently to RGB. Eyes are most sensitive to green light, less sensitive to red light, and the least sensitive to blue light. Therefore, the three colors should have different weights in the distribution. That brings us to the weighted method. The weighted method, also called luminosity method, weights red, green and blue according to their wavelengths. The improved formula is as follows:  $Grayscale = 0.299R + 0.587G + 0.114B$ . This transformation is useful in detecting blobs and further reduces the computational complexity. The critical task is to find a suitable threshold. There are two main methods, namely local and global thresholding.

### 1.3.2 Morphological Image Processing

It is a collection of non-linear operations related to the shape or morphology of features in an image. Morphological operations rely only on the relative ordering of pixel values, not on their numerical values, and therefore are especially suited to the processing of binary images. Morphological operations can also be applied to greyscale images such that their light transfer functions are unknown and therefore their absolute pixel values are of no or minor interest. Morphological techniques probe an image with a small shape or template called a structuring element. The structuring element is positioned at all possible locations in the image and it is compared with the corresponding neighborhood of pixels. Some operations test whether the element "fits" within the neighborhood, while others test whether it "hits" or intersects the neighborhood.

### 1.3.3 Convolution

Convolution is a simple mathematical operation which is fundamental to many common image processing operators. Convolution provides a way of 'multiplying together' two arrays of numbers, generally of different sizes, but of the same dimensionality, to produce a third array of numbers of the same dimensionality. This can be used in image processing to implement operators whose output pixel values are simple linear combinations of certain input pixel values.

In an image processing context, one of the input arrays is normally just a gray level image. The second array is usually much smaller, and is also two-dimensional (although it may be just a single pixel thick), and is known as the kernel. Figure 2, shows an example image and kernel that we will use to illustrate convolution.

Fig 2, An example small image (left) and kernel (right) to illustrate convolution. The labels within each grid

square are used to identify each square

The convolution is performed by sliding the kernel over the image, generally starting at the top left corner, so as to move the kernel through all the positions where the kernel fits entirely within the boundaries of the image. (Note that implementations differ in what they do at the edges of images, as explained below.) Each kernel position corresponds to a single output pixel, the value of which is calculated by multiplying together the kernel value and the underlying image pixel value for each of the cells in the kernel, and then adding all these numbers together. So, in our example, the value of the bottom right pixel in the output image will be given by:

$$O_{9,9} = I_{6,6}K_{1,1} + I_{6,7}K_{1,2} + I_{6,8}K_{1,3} + I_{6,6}K_{2,1} + I_{6,7}K_{2,2} + I_{6,8}K_{2,3}$$

I <sub>11</sub>	I <sub>12</sub>	I <sub>13</sub>	I <sub>14</sub>	I <sub>15</sub>	I <sub>16</sub>	I <sub>17</sub>	I <sub>18</sub>	I <sub>19</sub>
I <sub>21</sub>	I <sub>22</sub>	I <sub>23</sub>	I <sub>24</sub>	I <sub>25</sub>	I <sub>26</sub>	I <sub>27</sub>	I <sub>28</sub>	I <sub>29</sub>
I <sub>31</sub>	I <sub>32</sub>	I <sub>33</sub>	I <sub>34</sub>	I <sub>35</sub>	I <sub>36</sub>	I <sub>37</sub>	I <sub>38</sub>	I <sub>39</sub>
I <sub>41</sub>	I <sub>42</sub>	I <sub>43</sub>	I <sub>44</sub>	I <sub>45</sub>	I <sub>46</sub>	I <sub>47</sub>	I <sub>48</sub>	I <sub>49</sub>
I <sub>51</sub>	I <sub>52</sub>	I <sub>53</sub>	I <sub>54</sub>	I <sub>55</sub>	I <sub>56</sub>	I <sub>57</sub>	I <sub>58</sub>	I <sub>59</sub>
I <sub>61</sub>	I <sub>62</sub>	I <sub>63</sub>	I <sub>64</sub>	I <sub>65</sub>	I <sub>66</sub>	I <sub>67</sub>	I <sub>68</sub>	I <sub>69</sub>

K <sub>11</sub>	K <sub>12</sub>	K <sub>13</sub>
K <sub>21</sub>	K <sub>22</sub>	K <sub>23</sub>

### 1.3.4 Thinning of Image

Thinning is a morphological operation that is used to remove selected foreground pixels from binary images, somewhat like erosion or opening. It can be used for several applications, but is particularly useful for skeletonization. In this mode it is commonly used to tidy up the output of edge detectors by reducing all lines to single pixel thickness. Thinning is normally only applied to binary images, and produces another binary image as output. The thinning operation is related to the hit-and-miss transform, and so it is helpful to have an understanding of that operator before reading on.

## 1.4 Extraction of Characters

Image can be captured in different illumination condition. So, if text images are captured in different illumination effect. It is not possible to read the

text in image format. Here we use image processing tools to extract text from image. The main aim is to extract the characters in various illumination conditions. Text will be in printed paper. We will capture the image of printed paper. We use effective algorithm to extract characters from printed paper. This system scans the text by evaluating each and every line. System will extract word from image using image processing toolbox. As image is captured by webcam or camera. So, image is more prone to noise and other environ

mental interference.

Fig 3, Image after Thinning process

In order to extract text from image we will be using thresholding method. Image pre-processing steps are applied on images. Unwanted objects are removed. Bounding boxes is applied to text extracted. These texts are in image format. These images are converted to characters. System uses optical character recognition to extract characters from image. Character and number images are stored in directory.



The extracted text image is separated by bounding box. Each bounding box will contain each character or number. Each character or number is resized to image stored in directory. Extracted image and existing character image feature is compared. After comparison characters are detected. Finally detected characters are shown in text format. Optical character extraction is used to extract text from image. Here we will extract text from image at any lightening condition.

### 1.5 Recognition Using Template Matching

In the pattern matching process using the template matching method, to make the pattern matching on the vehicle plate number. Before doing the pattern matching process, first, use a data template (reference). This is reference data is alphabetical letters ranging from A to Z and numbers ranging from 0 to 9, which will be used later in comparison with object data, to be able to recognize and match the value of each character from the object data, in order to get maximum results, and by the value of each character from the object

data. To avoid mistakes in the process, if there are vehicles that have nine digits, then in this matching template process, nine digits are used as a reference for the number of digits, for the difference in each letter and number on the vehicle plate number. After determining the number of digits, then entering the reference data in the form of letters of the alphabet and numbers into each digit, to facilitate the process of comparison between object data with the reference data.

## III. ANALYSIS AND OBSERVATION

Actual plate	Predicted plate	Mismatched characters	Accuracy
KA04JY4411	KA04JY411	0	100%
KA41MB3313	KA41MB3313	0	100%
KA09W2187	KA09W2181	1	90%
KL41Q9587	KC41O9587	2	88%

Table 1

Efficiency Table

Total number of vehicles tested	Successful extraction by first trial	Successful extraction by multiple trial	Total successful extraction	Success Percentage
40	21	13	34	85

Table 2

Summary of test result of Automatic license plate recognition (ALPR).

#### IV. CONCLUSION

The designed hand-held security device is evaluated by testing the authorization of approximately 70 vehicles which includes both two wheelers as well as four wheelers. The list contains both private vehicles and taxis as their license plates are different in color. Whenever a vehicle arrives at the entry gate of the Institute, its authorization is checked using this device by taking the image containing its license plate. The result is summarized in the table I. Some numbers were detected in single trial while some others needed multiple trials for successful detection.

It is noted that, an option to add an unauthorized number to the database is also given in the GUI. When this option is pressed, a higher official will be notified the detection of an unauthorized vehicle through cloud communication. He will be able to add the number of this vehicle into the database of authorized vehicles. It is seen that the success of the result depends on the quality of the image. Some of the factors which can affect quality of image are identified as: Different fonts between the license plates, blurred and skewed images, lighting conditions, modified license plates etc.

#### REFERENCES

- [1] S. Du, M. Ibrahim, M. Shehata, and W. Badawy, "Automatic license plate recognition (ALPR): A state-of-the-art review," *IEEE Transactions on circuits and systems for video technology*, vol. 23, no. 2, pp. 311–325, 2012.
- [2] H. N. Do, M. -T. Vo, B. Q. Vuong, H. T. Pham, A. H. Nguyen, and H. Q. Luong, "Automatic license plate recognition using mobile device," in 2016 International
- [3] A. Mutholib, T. S. Gunawan, J. Chebil, and M. Kartiwi, "Development of portable automatic number plate recognition system on android mobile phone," in *IOP Conference Series: Materials Science and Engineering*, vol. 53, no. 1. IOP Publishing, 2013, p. 012066.
- [4] A. Conci, J. Carvalho, and T. Rauber, "A complete system for vehicle plate localization, segmentation and recognition in real life scene." *IEEE Latin America Transactions*, vol. 7, no. 5, pp. 497–506, 2009.
- [5] P. Patil, C. Kanagasabapathi, and S. S. Yellampalli, "Automatic number plate recognition system for vehicle identification," in 2017 International Conference on Electrical, Electronics, Communication, Computer, and Optimization Techniques (ICEECCOT). IEEE, 2017, pp. 431–434.
- [6] S. Saha, S. Basu, M. Nasipuri, and D. K. Basu, "License plate localization from vehicle images: An edge based multi-stage approach," *International Journal of Recent Trends in Engineering*, vol. 1, no. 1, p. 284, 2009.
- [7] S. Kumar, S. Agarwal, and K. Saurabh, "License plate recognition system for Indian vehicles," *International Journal of Information Technology*, vol. 1, no. 2, pp. 311–325, 2008.
- [8] H. Karwal and A. Girdhar, "Vehicle number plate detection system for Indian vehicles," in 2015 IEEE International Conference on Computational Intelligence & Communication Technology. IEEE, 2015, pp. 8–12.