

Performance Evaluation of the Dynamic Resource Allocation in Fog Computing

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ABSTRACT— Virtual Machine (VM) technology has matured, computational resources in Fog systems may be partitioned in fine granularity and allocated on demand, resulting in three technologies: Formulating a deadline-driven resource allocation problem using the Fog environment and VM resource isolation technologies, as well as reducing user payment. It also offered an error-tolerant strategy to ensure task completion within the deadline by analysing the upper bound of task execution length based on the possible inaccurate workload prediction. Validating its efficacy in a genuine VM-enabled cluster setting with various levels of competition. Fog computing makes it incredibly difficult to investigate both Fog and fog resource scheduling strategies in order to optimise resource utilization efficiency. users' Quality of Service requirements are met, and both resource suppliers and user's profit is maximized. The Cost Optimization Algorithm with Fog Management requires an economy that efficiently handles the service of several users while also being resource-efficient and profitable. It mixes long-term and short-term rentals, which cannot only meet quality-of-service standards in the face of fluctuating system workload. The system proposes a resource-renting model called Double-Quality- Guaranteed (DQG), which mixes long- term and short-term rentals.

IndexTerms—Fog, Cloud, VM, Resource allocation

I. INTRODUCTION

In Federated Vehicular Cloud Computing (FVCC), dynamic resource allocation having many problems like operating cost will be very high and delayed user requests and QoS also not that much good. Federated Vehicular Cloud Computing doesn't support IoT applications.

Fog computing is a kind of network architecture that connects cloud computing with the Internet of Things .It is used to enhance the system efficiency and security. Fog computing is

useful for when only selected data is required to send to the cloud. The selected data is useful for long term storage. Fog computing plays a vital role in IoT devices. It will allow the data transmission among IoT devices and cloud services. Always data transmission will be very faster because data will be stored in the network edge. Examples include Car to Car Consortium, Devices with Sensors, Cameras. So, in fog computing, dynamic resource allocation having many be good. Cost and Time will be less.

Fog computing moves computing systems and storage very closest to the devices, applications, components. Because of this latency is greatly reduced. Generally, IoT devices will produce huge data.

These devices are having less latency in fog computing. Since those are very nearest to the data source. Fog computing goal is to lower the latency and increase efficiencies.

Advantages:

Minimize the latency: Since it is very nearest to the data source, prevents system failures, manufacturing line shutdowns. It will do the quick alerts and reduce the danger for users.

Reduce the operating costs: Because of processing data in local, operating costs will be less.

Enhance security: Since fog nodes are deployed using same policies, it will provide enhanced security.

Fog Computing Applications

Smart/Connected car manufacturers: Fog computing plays a major role in connected vehicles. This feature will reduce the accidents and enhance the safe driving.

Industrial IoT (IIoT): All manufacturing plants relies on the fog computing to get and process the huge amount of data in the local instead of cloud. It will increase the good data accuracy.

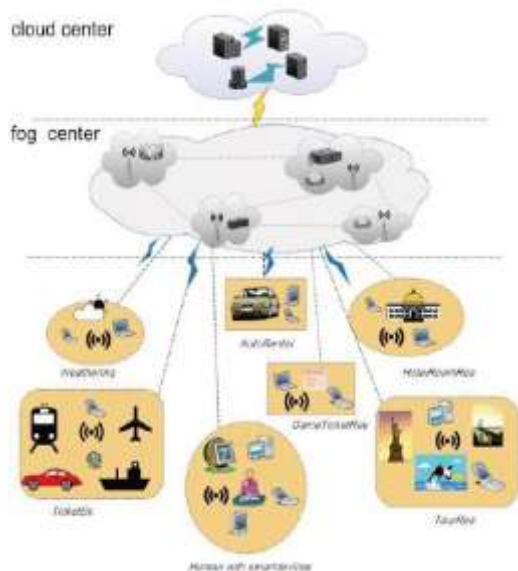
Smart cities and grids: Accurate data is essential in

all the systems which are available in smart cities. Using fog computing, sensor data will travel faster.

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Fog computing is a kind of network architecture that connects cloud computing with the Internet of Things. It is used to enhance the system efficiency and security. Fog computing is useful for when only selected data is required to send to the cloud. The selected data is useful for long term storage. Fog computing plays a vital role in IoT devices. It will allow the data transmission among IoT devices and cloud services. Always data transmission will be very faster because data will be stored in the network edge. Examples include Car to Car Consortium, Devices with Sensors, Cameras. So, in fog computing, dynamic resource allocation having many advantages like resource utilization and Quality of Service will

Fig.1 Fog Cloud Activation



II. LITERATURE SURVEY

EXISTING SYSTEM

The demerit of dynamically allocating resource in FVCC (Federated Vehicular Cloud Computing) doesn't support wide range of IoT applications and cost of the system is very high and doesn't provide better QoS. It does not handle more requests with lower cost.

A. Pricing-Based Strategic

FogPrime performs the existing methods in terms of utilization of resource and the cost. Due to the limitation of resources sub applications not served. Proposed scheme will serve all the services.

B. Resource Aware Cost-Efficient Scheduler

A Resource Aware Scheduler (RACE) performs for all work loads by means of minimum time execution, lower bandwidth, and less cost monetary. Here the challenge is bandwidth consumption and cost will be high when fog devices getting increased. This scheme will resolve bandwidth consumption and monetary cost issues.

C. Dynamic Resource Allocation and Computation Offloading for IoT

The average execution cost of the fog computing system can be minimized. The disadvantage here is the fog node will load the data to the cloud center if it does not have sufficient computational resources. The result shows that the proposed scheme handle its own even if it does not have enough computational resources.

D. A Contract-Matching Approach

Using Contract-Matching mechanism vehicles will share their resources and resolve the task assignment problem. Here the challenge is when the knowledge of channel and vehicle states are unknown, performance will not be good. In this scheme even if vehicle states are unknown, performance will be good.

E. Reinforcement Learning method using Heuristic Information

Here VFC algorithm is efficiently loading services to VFs in the long term. But the major problem with this approach is the Internet of Vehicle won't give service reliability for applications. Proposed scheme will give service reliability.

F. Predictive Offloading and Resource Allocation

Here the resource allocation not handled properly when wireless channel states are unknown. That causes stopping the entire decision-making process. Proposed scheme handles the decision making wisely even though wireless channel states are unknown.

G. Dynamic Energy Efficient Resource Allocation method or Load Balancing

Here using Dynamic Energy Efficient Resource Allocation (DEER) strategy is a good resource allocation method for load balancing in fog environments for reducing the consumption of energy and cost. Here the challenge is Fault-

tolerant resource allocation method is not available in fog environments. Proposed scheme will handle Fault-tolerant based issues.

H. Resource Management using a Novel Bio-Inspired Hybrid Algorithm (NBIHA)

This paper talks about the effective utilization of resources in fog-IoT using a novel hybrid resource management approach (NBIHA). But No facility available to avail the reinforcement learning techniques to manage the resources in the fog-IoT environment. Proposed scheme will support for organizing resources in the fog-IoT environment.

III. PROPOSED METHOD

In fog computing, dynamic resource allocation method using Resource Allocation Algorithm to increase the utilization of fog resources and provide better Quality of Service requirements.

This technique used to predict task completion time and allocate fog resources dynamically.

The important benefit of this resource allocation method is that the resources will be allocated without any error and resources will be allocated in less time and less cost.

The Cost Optimization Algorithm with Fog Management requires an economy that efficiently handles the service of several users while also being resource-efficient and profitable. It mixes long-term and short-term rentals, which cannot only meet quality-of-service standards in the face of fluctuating system workload. The system proposes a resource-renting model called Double-Quality- Guaranteed (DQG), which mixes long-term and short-term rentals.

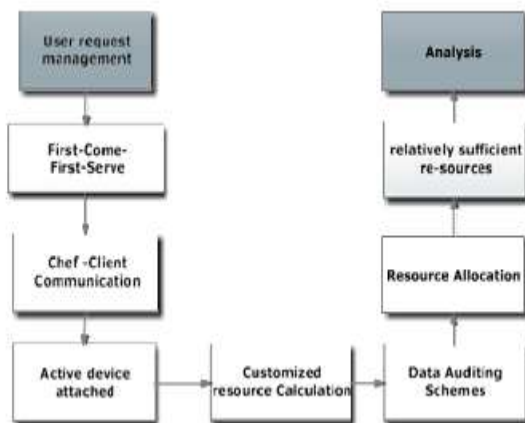


Fig.2 Architecture Diagram.

User Request Management

The cloud proxy receives and replies to user requests (or tasks) with tailored requirements

on a continuous basis in cloud systems (or virtual machines).

When jobs have the same priority, they will be processed according to their priorities (like task scheduler) or

according to the First-Come-First-Serve (FCFS) policy. The execution of each task may require several resources, such as CPU and disc I/O.

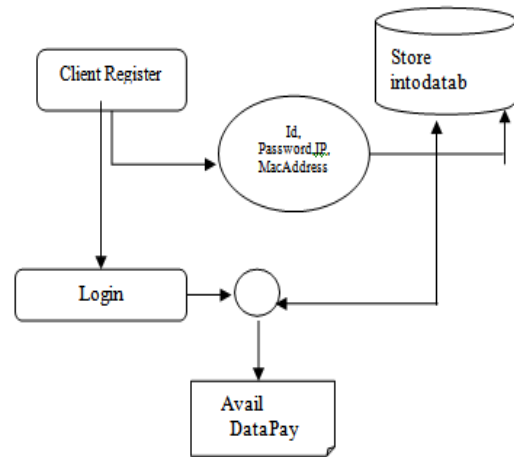


Fig.3 BlockDiagram of user request management.

Send to CloudSerer

2BlockDiagramofProposedmethod.

Chef-Client Communication

A physical node can be a server or a virtual machine, but it can also be any active device connected to a network that can send, receive, and forward data across a communications channel. To put it another way, a physical node is any active device connected to a network that can execute a chef-client and communicate with a server.

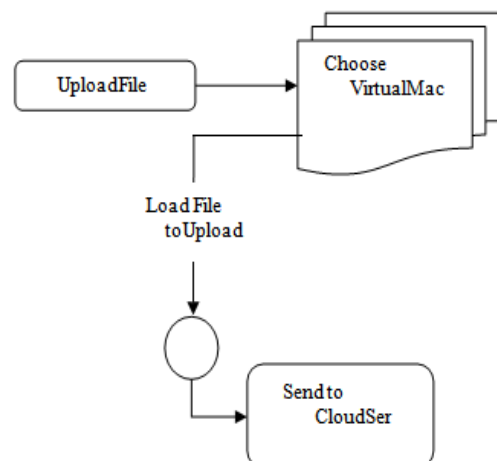
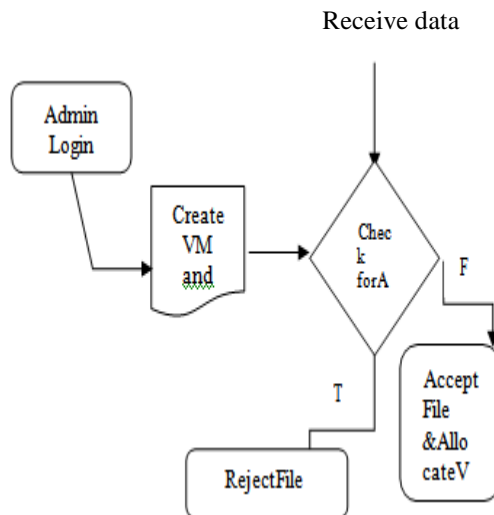


Fig.4 Block Diagram of Chef-Client communication.

Customized resource Calculation

Any work will be conducted on one or more virtual machines with user- to the protection of data auditing systems, the cloud server will not deliberately destroy or modify user data but will attempt to understand the substance of the stored data as well as the identities of cloud users.

Fig.5 Block Diagram of customized resource calculation



Data Auditing Schemes

In this lesson, local cloud will be set up and offer reasonably priced storage. Users can upload their information to the cloud. This module to make cloud storage safer. Users, on the other hand, do not fully trust the cloud because CSPs are very likely to be outside of the trusted domain of cloud users. That is, due to the protection of data auditing systems, the cloud server will not deliberately destroy or modify user data but will attempt to understand the substance of the stored data as well as the identities of cloud users.

Resource Allocation

Although this module demonstrated to be the most cost-effective for lowering payment costs within the deadline for their assignment, the deadline may not be guaranteed due to two factors: limited resources availability or faulty workload vector information about the task. Proposed effective technique that guarantees the task's deadline under the necessary and sufficient conditions of accurate forecast and comparatively sufficient resources.

The Algorithms

The allocation technique allows for resource provisioning to be automated. The difficulty that the FogCloud operator has is determining the most appropriate physical and virtual resources to serve these applications while adhering to the previously agreed-upon parameters. This cloud system resource allocation technique supports Virtual Machine multiplexing technology, which seeks to reduce task payment by users. According to the algorithm, the most important aspect is the local optimal resource allocation for execution on a specific node. In reality, the entire algorithm's ultimate outputted resource allocation solution will be globally optimal over the entire system as long as each local process on a given node can be proven to be optimal resource allocation. As a result, by selecting a specific execution node, this will go over the local divisible-resource allocation in depth.

Algorithm 1: Optimal allocation algorithm

Optimal allocation algorithm

- Input: $D(t)$; Output: execution node $p_s, r^*(t)$
- $\Gamma = \Pi, C = D(t), r^* = \phi$ (empty set);
- Repeat
- $r_r^*(t, p_s) = \text{CO-STEP}(\Gamma, c)$;
- on Γ^*
- $\Omega = d_s / d_s \in \Gamma \ \& \ r_r^{(s)}(t, p_s) > a_s(p_s)$;
- $\Gamma = \Gamma \setminus \Omega$ / Γ take away Ω /
- $C = C - \theta \sum_{s \in \Omega} \frac{I_s}{\mu_s}$ / Update C^* /
- $r^*(t, p_s) = r^*(t, p_s) \cup \{r_r^{(s)} = a_s(p_s)\}$;
- is d_s 's upper bound];
- until $(\Omega = \phi)$;
- $r^*(t, p_s) = r^*(t, p_s) \cup r_r^*(t, p_s)$
- end for
- Select the smallest $p(t)$ by traversing the candidate solution set;
- Output the selected node p_s and resource allocation $r^*(t, p_s)$;

Fig.6 Pseudocode of Allocation mechanism

Algorithm 2: Prediction for the Task's Completion Time (PTCT)

Input: APT

PNTask. Output: The time cost $\tau(\sigma)$ of a sequence σ .

- 1: construct a new Petri net which only has the places and transitions of PT PNTask based on PT PNTask
- 2: for each transition t in sequence σ do
- 3: if the arc associated with t does not in the Petri net then
- 4: add the arc to the net
- 5: end if
- 6: end for
- 7: achieve a subnet of PT PNTask

8:denotethisnewPetri netmodelasSPTPNT
 askwhichdoesnotexistconflicttransition
 9:foreachbasicsequential,concurrentandloopstructur
 esinSPT PNTtask do
 10:repeat
 11:conductthesimplificationprocessesinaccordance
 withFig.10(a), (b),(c)respectively
 12: until the resulted non-conflict structured net
 illustrated inFig.11isobtained
 13:endfor
 14:thetimecostofsequence σ is $\tau(\sigma)$ 15:return $\tau(\sigma)$



Fig.7DataFlowDiagram of proposedmethod.

IV. RESULT AND ANALYSIS

Interms ofusertaskcompletionprobability,comparedo
 uralgorithm MFR to the standard multi-user work
 scheduling methods
 MinminandMaxmin[7].Thenumbersinparenthesis
 on the graph represent thealgorithm's average
 performance. MFRhas a mean of 0.986, with
 Minmin andMaxmin both at 0.938. As seen in
 thegraph, our method MFR has a higherlikelihood
 of finishing tasks than
 theothertwoalgorithms,andinmostcasesitisuperiort
 o them.

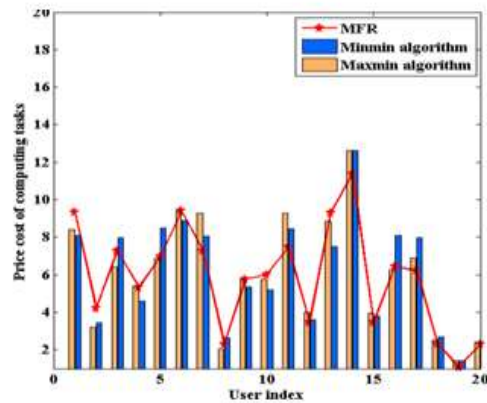


Fig. 8 shows the comparison between PredictionfortheTask’sCompletionTimealgorithm MFR,

In terms of the cost of accomplishing a user job, Minmin and Maxmin are the best options. As can be seen from the graph, the pricing cost of MFR to accomplish the task for any user is lower than the other two algorithms in all but a few cases (user1, user2, and user13). MFR, Minmin, and Maxmin had mean values of 5.85, 6.08, and 6.03, respectively.



Fig. 9 Resource allocation output

V. CONCLUSION

The workexamines thepractical problem ofdynamic resource allocation strategy for vehicular cloud computing, having many problems like operating cost will be very high and delayed user requests and QoS also not that much good. Federated vehicular cloud computing does not support IoT applications. Fog Computing provides the option to improve the resource utilization efficiency, better user’s Quality of Service requirements increase the profit of both resource providers and users. A resource allocation algorithm has the good error tolerance ability, also

reducing users payment within the deadlines. Moreover, this method used to predict task completion time, compute resources evaluation and allocate fog resources dynamically. This scheme can provide good resource selection for user's task scheduling and enhance the utilization of fog resources. The idle physical resources can be arbitrarily partitioned and allocated to new tasks; the VM-based divisible resource allocation could be very flexible.

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