

Smart Parking with Wireless Charging for Electric-Vehicle

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Submitted: 05-05-2022

Revised: 10-05-2022

Accepted: 13-05-2022

ABSTRACT – Nowadays, There was rapid increase in vehicle's fuel cost and demand when we compared to last decade [1]. If this situation continues for next few decades, there is more chance in lack of vehicle's fuel [2]. So to avoid that worst scenario in our world, our world is moving towards usage of electrical vehicle and all vehicle manufacturers are encouraged to manufacture electrical vehicles [3]. In this manufacturing of E-vehicles, the charging of battery is done by two method: wired and wireless charging method [4]. Due to more advantages and reliable operation, wireless charging is predominantly selected by E-vehicles manufacturers. This project "smart parking with wireless charging of e-vehicles" have its wireless charging under the principle called "mutual inductance" [5]. And advance to our project, we added the facility of, "smart parking of electrical vehicles" it happens when the electrical vehicle parked within range of IR sensor placed in charging point and stepper motor help this smart parking process of four electrical vehicles [6].

Keywords: E-

Vehicle, Electric Automobile, Mutual Inductance, Infrared Sensor, Coil Charging, Wireless technology.

I. INTRODUCTION

Normally, our world is moving towards usage of electrical vehicles in order to escape from the danger of shortage of fuel like petrol, diesel, etc. in order to achieve this electrical vehicle to be more reliable and affordable, many researchers are in race to show their best under above mentioned motive. One of the most important assets of the electrical vehicles is battery. This is the important thing that should be designed in reliable manner. The main motive in this battery should be designed like, "charging speed should be high with large capacity batteries too", in order to achieve the situation that we can travel long distance by our electrical vehicle by less charging time. If this

situation comes in reality, then that day will be the remarked as the great success of electrical vehicle and this makes more reliable to use by consumers. The

product's success is depends on reliable usage of the consumer. This should be the primary target for our research teams in electrical vehicles. Then, the next target is to make this charging by wirelessly by, "wireless charging method of electrical vehicles". This wireless charging method comes with more advances side than the wired method of charging electrical vehicles. So, the charging of electrical vehicles wirelessly consist of more types like static, dynamic, capacitance, etc. Here we are charging of electrical vehicles under the principle called, "mutual inductance". The charging of electrical vehicles in this method is similar to the transformer electric transformation, since we using here, "mutual inductance" principle. And let's move on to our additional facility, "smart parking", that really makes more comfortable to this wireless charging setup. It consist of IR sensor and stepper motor which help electrical vehicle to park automatically to charging point if they are in range to our charging point. Existing system of charging of electrical vehicles is, "wired charging method". Even though it was succeed in charging of electrical vehicles, it comes with more disadvantages like high in initial cost, not much reliable, mechanical strength of this setup is not much stronger, harmful and high risk of electrical accidents, more on. So, this system of charging electrical vehicles is not much effective. Research team of electrical vehicles made decision to make next level of charging type of electrical vehicles.

II. PROBLEM FORMULATION OF SMART PARKING

After more research made by research teams of electrical vehicles, we achieved the next level of charging of electrical vehicles, "wireless charging of electrical vehicles". It becomes so advantages

when compared to wired charging of electrical vehicles. It has reliable performance, less loss and more efficient, more safety setup than compared to wired charging of electrical vehicles. So due to those with smart parking facility, so it will be automated parking within certain range of IR sensor of

charging point. With this smart parking type facility of electrical vehicles and wireless charging of electrical vehicles, our project is on whole another level of success in electrical vehicles field.

III. BLOCK DIAGRAM

Smart parking part:



Fig. 1, Smart parking part WIRELESS CHARGING PART:

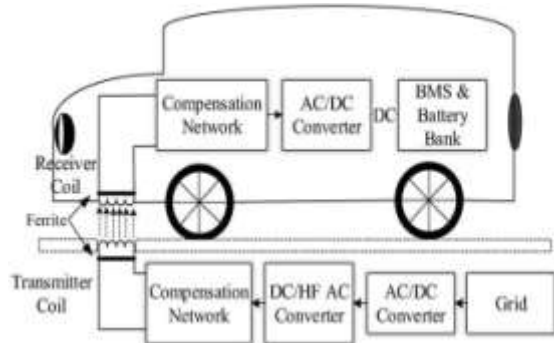


Fig. 2, Wireless charging part

At first, 220 volt, 50Hz, is provided from Supply Grid. This AC voltage is converted into DC Voltage by using AC-DC Converter. And that converted DC Voltage is converted into High Voltage Alternating Current (HVAC) and fed into the Transmitter coil. After this process, Alternating magnetic field produced, and when coil cuts magnetic field, EMF transmitted to the Receiver Coil. During this process, the Resonance Frequency should be compensated to smooth transmission of supply from transmission coil to receiving coil by providing Compensation Network to both coil Transmitter and Receiver respectively. After receiving this AC Voltage from Transmitter coil, it is converted into DC voltage by using AC-DC Converter. And this DC Supply is saved or stored in Battery using Battery Management System (BMS). By this whole process, the wireless charging of

so much advantages, vehicle manufacturers are more encouraged to make wireless charging setup in electrical vehicles. It works in the principle of, "mutual inductance". And also our project is linked Electrical vehicles using, "Mutual Inductance", Takes Places in Comfortable manner.

1. Implementation of Smart Parking with Wireless Charging

In order to achieve efficient charging of electrical vehicles, wireless charging of electrical vehicles will be the best solution. Here we discuss about implementation on smart parking with wireless charging of electrical vehicles. "Mutual inductance" is the principle used in wireless charging of electrical vehicles. The charging point was made by Arduino Uno, infrared sensor, stepper motor,

smart electrical vehicle supply equipment (SEVSE). Infrared ray sensor will sense the electrical vehicle that parked near the charging point. Maximum range of infrared sensor will be 10 meters for reliable operation of sensory unit. After sensing the electrical vehicles, infrared sensor will give signal to stepper motor. This stepper motor will make adjustment

in positioning of electrical vehicle to achieve comfortable parking to the wireless charging point. After this successful parking, wireless charging takes place. Smart electrical vehicle supply equipment (SEVSE) is like connection of battery with supply source. The wireless charging of electrical vehicles was made by supply source, transmitter and receiver coils, rectifier and inverters, battery banks and battery monitoring system (BMS). Initially 220v, 50hz, AC supply taken from supply source and fed to rectifier. This converted AC supply into DC supply. This DC supply again converted into high voltage alternating current (HVAC) by inverter and fed to the transmitter coil. Now, magnetic field will be produced when transmitter coil energised. When coil cuts the magnetic field, EMF induced in it. Voltage supply will be generated by EMF

and transmitted to receiver coil. After receiver coil receives AC supply from transmitter coil, this AC voltage is converted into DC voltage by rectifier. This converted DC voltage will be stored or charged by batteries of electrical vehicles as per their power ratings through battery monitoring system and battery banks. This battery monitoring system (BMS) will be vital part of wireless charging of electrical vehicle system because it monitors, protects the batteries of electrical vehicles from hazards. These are all the implementations that we have done in smart parking and wireless charging of electrical vehicles.

IV. RESULTS AND DISCUSSION

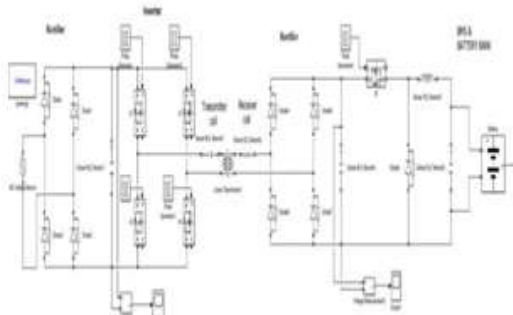


Fig.3,Simulationcircuit

Time period in Ms	0	1.255	1.26
Transmitter voltage(V)	130	230	45

Fig.3, represent the simulation circuit diagram of "Smart parking with wireless charging of electrical vehicles". It is clear that this simulation consist of three parts: transmitter part, receiver part and battery monitoring system. In transmitter part, it consist of supply source, rectifier, inverter, transmitter coil. When we clearly watch this figure, supply source 230v, 50hz Ac Supply is fed to 'rectifier' and it rectified into dc voltage. Now, this dc voltage is again converter into high voltage ac supply by 'inverter' and fed into the transmitter coil. Now, these second part is receiver part of this simulation circuit. If we look carefully, the receiver coil and transmitter coil is placed same as transformer since using the same principle "mutual inductance". So when the transmitter coil cuts the magnetic field with receiver coil, it create magnetic field and by controlling resonance frequency with compensating networks, the supply voltage is transmitted to receiver coil. Now the third and final part of this simulation circuit is battery monitoring system (BMS). It consist of Rectifier, Battery bank & Battery monitoring system (BMS). Rectifier is used to convert Ac supply received by receiver coil to dc voltage. Now this dc voltage is stored in the battery and monitored carefully to protect it from hazards by battery monitoring system.

**Simulation output wave forms:
 Transmitter Waveform:**

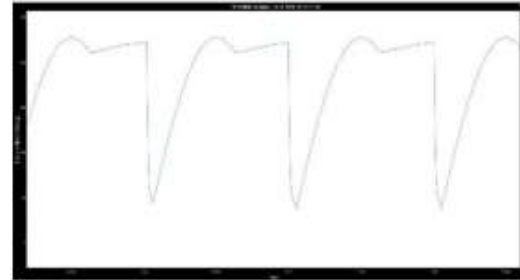


Fig.4, Transmitter voltage Waveform

Time period in Ms	0	1.255	1.26
Transmitter voltage(V)	130	230	45

Fig.5, Transmitter voltage tabular column

Figure 5, shows clearly that at initial time period, the voltage rises to 130 volts. After 1.255 (ms) time period reached, the voltage rises rapidly to 230 volts. After few milli second time period, at 1.26 milli second, the voltage dropped to 45 volts. These oscillations in voltages are repeated continuously with time period in milli second.

Receiver Waveform:

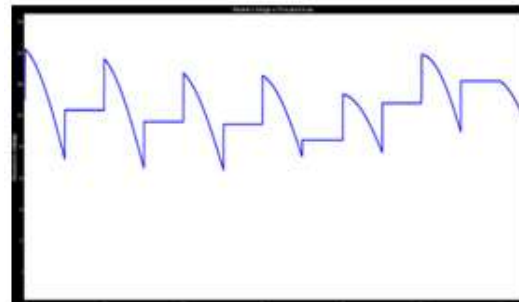


Fig.6, Receiver Waveform:

Time period in ms	1.54	1.55	1.56
Receiver's Voltage	142	70	138

Fig.7, Receiver Waveform tabular column

Figure 7 (Receiver's voltage tabular column) represents clearly the oscillations in receiver's voltage with respect to its time. From this tabular column, we can see that voltage increased to 142 volts, at 1.54 milli seconds time period. After few time period in milli second, voltage reduced to 70 volts, at 1.55 milli second time period. Again, voltage increased to 138 volts at 1.56 milli seconds in time period. So we clearly see the oscillations up and down in voltage with respect to its time

period in ms.

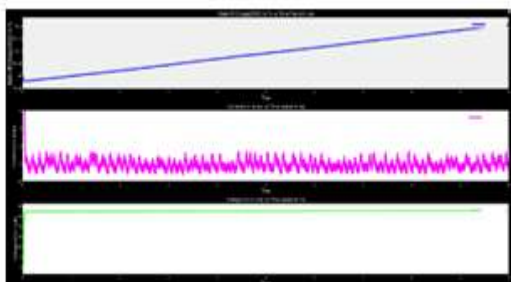


Fig8, Battery monitoring system waveform

Tabular column of Soc (%) vs Time period in ms

Time period in ms	0.1	1	2
Soc (%)	79.98	80	8.03

Fig9, Tabular column of state of charge in % vs Time period in

Figure 9 (Tabular column of state of charge in %) clearly represents that state of charge percentage of battery is rising or increasing gradually with increase in time period in ms. If we look on tabular column, it denotes that at 0.1 milli second time period, state of charge of battery reaches 79.98%. After gradual increase in time period, state of charge will also increase gradually as shown in above tabular column.

Tabular column of current (I) in amps vs time period in ms:

Time period in ms	0.1	1	2
current (I) in amps	10	-7	-2

Fig 10, Tabular column of current (I) in amps vs time period in ms

Figure 10 (Tabular column of current (I) in amps vs time period in ms) represents those current reaches 10 amps at initial time period 0.1 milli seconds. When time period increased to 1 milli seconds, then current reduced to negative amps. Then after 2 milliseconds, the current moved near to positive amps. This oscillations in current will be continued throughout signals at mentioned intervals in above tabular column.

State Of Charge waveform:

Tabular column of voltage (v) in volts vs time period in ms:

time period in ms	0.1	1	2
Voltage (v) in volts	55	55	55

Figure 11, Tabular column of voltage in volts vs time period in ms

Figure 11 (Tabular column of voltage in volts vs time period in ms) represents that voltage reaches to 55 volts at initial time period 0.1 milliseconds. After 1 millisecond time period, the voltage is maintained constant 55 volts, even there is increase in time period in milli second as we clearly see it in above tabular column.

V. CONCLUSION

The main outcome of our project is to Charge our Electrical vehicle's Battery 'Wirelessly' and to park our Electrical vehicles automatically or Smartly to the Grid of power supply. If our Electrical vehicle is parked inside IR Sensor's Range. By doing our Project Successfully, we can achieve this Comfortable charging facility and we need to research more on it to enhance more advanced features and technologies that will be helpful in our future life. By More research on this Project, to reduce the possible errors and Malfunction in "Smart parking and wireless charging of electrical vehicles" We can achieve more flawless and Comfortable Charging method for Electrical vehicles. By Creating More Awareness on wireless charging method of electrical vehicles to all vehicle Manufacturers, surely it makes them to manufacture the upcoming Electrical Vehicles with wireless charging facility. In addition to this, If Smart parking too made in Charging point, then this whole charging setup will be more Comfortable manner and Easy method to proceed Wireless Charging of electrical vehicle.

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